

## Problem Set 4 – Solutions

**Problem 1.** (a) Let  $x \in S^n$ . We have  $x_1^2 + \cdots + x_{n+1}^2 = 1$ . Hence  $x_j \neq 0$  for some  $j \in \{1, \dots, n+1\}$ . Thus either  $x_j > 0$  or  $x_j < 0$  for some  $j \in \{1, \dots, n+1\}$ . This implies that either  $x \in \mathcal{U}_j$  or  $x \in \mathcal{V}_j$  for some  $j \in \{1, \dots, n+1\}$ . That is  $x \in \mathcal{U}_j \cup \mathcal{V}_j$  for some  $j \in \{1, \dots, n+1\}$ . Hence  $x \in \bigcup_{j=1}^{n+1} \mathcal{U}_j \cup \mathcal{V}_j$ . Thus  $S^n \subset \bigcup_{j=1}^n \mathcal{U}_j \cup \mathcal{V}_j$ . Clearly  $\bigcup_{j=1}^n \mathcal{U}_j \cup \mathcal{V}_j \subset S^n$ . Therefore  $S^n = \bigcup_{j=1}^n \mathcal{U}_j \cup \mathcal{V}_j$ . We observe that  $\varphi_j$  and  $\psi_j$  are invertible on  $\varphi_j(\mathcal{U}_j)$  and  $\psi_j(\mathcal{V}_j)$  with

$$\begin{aligned} & \varphi_j^{-1}(y_1, \dots, y_n) \\ &= (y_1, \dots, y_{j-1}, \sqrt{1 - (y_1^2 + \cdots + y_n^2)}, y_j, \dots, y_n), \\ & \psi_j^{-1}(y_1, \dots, y_n) \\ &= (y_1, \dots, y_{j-1}, -\sqrt{1 - (y_1^2 + \cdots + y_n^2)}, y_j, \dots, y_n). \end{aligned}$$

It follows that  $\varphi_j$  and  $\psi_j$  are homeomorphisms. We observe that  $\mathcal{U}_j$  and  $\mathcal{V}_j$  are connected. Thus  $(\mathcal{U}_j, \varphi_j)$  and  $(\mathcal{V}_j, \psi_j)$  are charts. To prove that these charts are compatible we need to verify that  $\varphi_j \circ \varphi_k^{-1}$ ,  $\varphi_j \circ \psi_k^{-1}$ ,  $\psi_j \circ \psi_k^{-1}$  and  $\psi_j \circ \varphi_k^{-1}$  are smooth. We consider  $\varphi_j \circ \varphi_k^{-1}$  for  $j < k$ . The other cases are similar. We have

$$\begin{aligned} & \varphi_j \circ \varphi_k^{-1}(y_1, \dots, y_n) \\ &= \varphi_j(y_1, \dots, y_{k-1}, \sqrt{1 - (y_1^2 + \cdots + y_n^2)}, y_k, \dots, y_n) \\ &= (y_1, \dots, y_{j-1}, y_{j+1}, \dots, y_{k-1}, \sqrt{1 - (y_1^2 + \cdots + y_n^2)}, y_k, \dots, y_n). \end{aligned}$$

It is simple to verify that this mapping is smooth. Combining all this we conclude that  $\mathcal{A}_1$  is an atlas for  $S^n$ .

(b) Let  $x \in S^n$ . If  $x_{n+1} = 1$ , then  $x \in \mathcal{V}$ , else  $x \in \mathcal{U}$ . Thus  $x \in \mathcal{U} \cup \mathcal{V}$ . Hence  $S^n \subset \mathcal{U} \cup \mathcal{V}$ . Clearly  $\mathcal{U} \cup \mathcal{V} \subset S^n$ . Therefore  $S^n = \mathcal{U} \cup \mathcal{V}$ .

We now prove that  $\varphi$  and  $\psi$  are homeomorphisms. We give the details of the proof only for  $\varphi$ . The proof for  $\psi$  is similar. Let  $y = \varphi(x)$ . We have

$$y_j = \frac{2x_j}{1 - x_{n+1}}$$

for  $j = 1, \dots, n$ . We calculate

$$\begin{aligned} |y|^2 &= \frac{4}{(1-x_{n+1})^2}(|x|^2 - x_{n+1}^2) \\ &= \frac{4}{(1-x_{n+1})^2}(1-x_{n+1}^2) \\ &= \frac{4}{(1-x_{n+1})^2}((1-x_{n+1})^2 + 2x_{n+1}(1-x_{n+1})) \\ &= 4 + \frac{8x_{n+1}}{1-x_{n+1}}. \end{aligned}$$

Solving this equation for  $x_{n+1}$ , we obtain

$$x_{n+1} = \frac{|y|^2 - 4}{|y|^2 + 4}.$$

Hence

$$x_j = \frac{4y_j}{|y|^2 + 4}$$

for  $j = 1, \dots, n$ . Thus, for  $y \in \varphi(\mathcal{U})$ , we have

$$\varphi^{-1}(y) = \left( \frac{4y_1}{|y|^2 + 4}, \dots, \frac{4y_n}{|y|^2 + 4}, \frac{|y|^2 - 4}{|y|^2 + 4} \right).$$

In fact, it follows that  $\varphi \circ \varphi^{-1}(y) = y$  and  $\varphi^{-1} \circ \varphi(x) = x$ . It is simple to verify that  $\varphi$  is differentiable. Thus it follows that  $\varphi$  is a homeomorphism. Similarly we find that

$$\psi^{-1}(y) = \left( \frac{4y_1}{|y|^2 + 4}, \dots, \frac{4y_n}{|y|^2 + 4}, \frac{4 - |y|^2}{|y|^2 + 4} \right)$$

for  $y \in \psi(\mathcal{V})$ . It follows that  $\psi$  is a homeomorphism. We observe that  $\mathcal{U}$  and  $\mathcal{V}$  are connected. Thus  $(\mathcal{U}, \varphi)$  and  $(\mathcal{V}, \psi)$  are charts. To prove that these charts are compatible we need to verify that  $\varphi \circ \psi^{-1}$  and  $\psi \circ \varphi^{-1}$  are smooth. We consider  $\varphi \circ \psi^{-1}$ . The other case is similar. We have

$$\begin{aligned} (\varphi \circ \psi^{-1})_j(y) &= \varphi_j \left( \frac{4y_1}{|y|^2 + 4}, \dots, \frac{4y_n}{|y|^2 + 4}, \frac{4 - |y|^2}{|y|^2 + 4} \right) \\ &= 2 \frac{4y_j}{|y|^2 + 4} \left( 1 - \frac{4 - |y|^2}{|y|^2 + 4} \right)^{-1} \\ &= \frac{4y_j}{|y|^2}. \end{aligned}$$

We observe that  $|y| \neq 0$ . It is simple to verify that this mapping is smooth. We conclude that  $\mathcal{A}_2$  is an atlas.

(c) By proceeding similarly as in Part (b), we obtain

$$(\psi \circ \varphi^{-1})(y) = \frac{4}{|y|^2}y.$$

(d) Consider the chart  $(\mathcal{U}_j, \varphi_j)$ . For  $k = 1, \dots, n$ , the vector

$$\frac{\partial \varphi_j^{-1}}{\partial y_k}(y) \in \mathbb{R}^{n+1}$$

corresponds to the tangent vector

$$\frac{\partial}{\partial y_k} \in T_{\varphi_j(y)}S^n.$$

We calculate

$$\begin{aligned} \frac{\partial \varphi_j^{-1}}{\partial y_k}(y) &= \left( \frac{\partial y_1}{\partial y_k}, \dots, \frac{\partial y_{j-1}}{\partial y_k}, \frac{\partial}{\partial y_k} \sqrt{1 - |y|^2}, \frac{\partial y_j}{\partial x_k}, \dots, \frac{\partial y_n}{\partial y_k} \right) \\ &= \left( \delta_{1,k}, \dots, \delta_{j-1,k}, \frac{-y_k}{\sqrt{1 - |y|^2}}, \delta_{j,k}, \dots, \delta_{n,k} \right) \end{aligned}$$

Similarly we obtain

$$\frac{\partial \psi^{-1}}{\partial y_k}(y) = \left( \delta_{1,k}, \dots, \delta_{j-1,k}, \frac{y_k}{\sqrt{1 - |y|^2}}, \delta_{j,k}, \dots, \delta_{n,k} \right).$$

(e) Working in  $S^1$  with the atlas  $\mathcal{A}_1$ , we have four charts:

$$\mathcal{A}_1 = \{(\varphi_1, \mathcal{U}_1), (\varphi_2, \mathcal{U}_2), (\psi_1, \mathcal{V}_1), (\psi_2, \mathcal{V}_2)\}.$$

Consider the chart  $(\varphi_1, \mathcal{A}_1)$ . We have

$$\varphi_1(x_1, x_2) = x_2$$

and

$$\varphi_1^{-1}(y_1) = (\sqrt{1 - y_1^2}, y_1).$$

Hence  $\frac{\partial}{\partial y_1}$  corresponds to

$$\frac{\partial \varphi_1^{-1}}{\partial y_1}(y_1) = \left( \frac{-y_1}{\sqrt{1 - y_1^2}}, 1 \right).$$

(Similarly we calculate  $\partial/\partial y_1$  on the other charts.) Thus

$$g_{11}(y_1) = \left\langle \frac{\partial \varphi_1^{-1}}{\partial y_1}(y_1), \frac{\partial \varphi_1^{-1}}{\partial y_1}(y_1) \right\rangle = \frac{1}{1 - y_1^2}$$

and

$$g^{11}(y_1) = g_{11}^{-1}(y_1) = 1 - y_1^2.$$

(Similarly we obtain the same expressions for  $g_{11}$  and  $g^{11}$  on the other charts.) Furthermore

$$\text{grad}(f) = g^{11} \frac{\partial f}{\partial y_1} \frac{\partial}{\partial y_1} = (1 - y_1^2) \frac{\partial f}{\partial y_1} \frac{\partial}{\partial y_1}$$

and

$$\text{div}(X) = \frac{1}{\sqrt{g}} \frac{\partial}{\partial y_1} (\sqrt{g} X^1)$$

where

$$X = X^1 \frac{\partial}{\partial y_1}.$$

Hence

$$\begin{aligned} \Delta_g(f) &= \text{div}(\text{grad}(f)) \\ &= \sqrt{1 - y_1^2} \frac{\partial}{\partial y_1} \left( \sqrt{1 - y_1^2} \frac{\partial f}{\partial y_1} \right) = (1 - y_1^2) \frac{\partial^2 f}{\partial y_1^2} - y_1 \frac{\partial f}{\partial y_1}. \end{aligned}$$

Therefore

$$\Delta_g = (1 - y_1^2) \frac{\partial^2}{\partial y_1^2} - y_1 \frac{\partial}{\partial y_1}.$$

(Similarly we obtain the *same* expression on the other charts.)

**Problem 2.** Let  $(x_1, \dots, x_m)$  be a coordinate system for  $M$ , and let  $(y_1, \dots, y_n)$  be a coordinate system for  $N$ . We first calculate

$$\begin{aligned} \left( \Phi_* \frac{\partial}{\partial x_j} \right) f &= \frac{\partial}{\partial x_j} (\Phi^* f) = \frac{\partial}{\partial x_j} (f \circ \Phi) = \sum_{k=1}^n \frac{\partial f}{\partial y_k} \frac{\partial \Phi_k}{\partial x_j} \\ &= \left( \sum_{k=1}^n \frac{\partial \Phi_k}{\partial x_j} \frac{\partial}{\partial y_k} \right) f. \end{aligned}$$

Now, since  $\Phi^* g_N = g_M$ , we have

$$\begin{aligned} g_{ij}^M &= g_M \left( \frac{\partial}{\partial x_i}, \frac{\partial}{\partial x_j} \right) = \Phi^* g_N \left( \frac{\partial}{\partial x_i}, \frac{\partial}{\partial x_j} \right) \\ &= g_N \left( \Phi_* \frac{\partial}{\partial x_i}, \Phi_* \frac{\partial}{\partial x_j} \right) = g_N \left( \sum_{k=1}^n \frac{\partial \Phi_k}{\partial x_i} \frac{\partial}{\partial y_k}, \sum_{l=1}^n \frac{\partial \Phi_l}{\partial x_j} \frac{\partial}{\partial y_l} \right) \\ &= \sum_{k=1}^n \frac{\partial \Phi_k}{\partial x_i} \sum_{l=1}^n g^N \left( \frac{\partial}{\partial y_k}, \frac{\partial}{\partial y_l} \right) \frac{\partial \Phi_l}{\partial x_j} \\ &= [D\Phi^T G_N D\Phi]_{ij}. \end{aligned}$$

Hence

$$G_M = D\Phi^T G_N D\Phi.$$

This implies  $\det(D\Phi) \neq 0$ . Thus  $D\Phi$  is a local isomorphism. Hence, by the inverse function theorem, the mapping  $\Phi$  is a local diffeomorphism. In addition, the equality

$$D\Phi(\Phi^{-1}(q))^{-1} D\Phi(\Phi^{-1}(q)) = I$$

implies

$$D\Phi^{-1}(q) D\Phi(\Phi^{-1}(q)) = I$$

because  $D\Phi(\Phi^{-1}(q))^{-1} = D\Phi^{-1}(q)$ .

(a) Using the above observations, we obtain

$$\begin{aligned} \Phi_*(\text{grad}_{g_M} \Phi^* f) &= \Phi_*(\text{grad}_{g_M} f \circ \Phi) \\ &= \Phi_* \left( \sum_{j=1}^m (\text{grad}_{g_M} f \circ \Phi)^j \frac{\partial}{\partial x_j} \right) \\ &= \Phi_* \left( \sum_{j=1}^m \sum_{k=1}^m g_M^{jk} \frac{\partial}{\partial x_k} (f \circ \Phi) \frac{\partial}{\partial x_j} \right) \\ &= \sum_{j=1}^m \sum_{k=1}^m g_M^{jk} \sum_{l=1}^n \frac{\partial f}{\partial y_l} \frac{\partial \Phi_l}{\partial x_k} \Phi_* \frac{\partial}{\partial x_j} \\ &= \sum_{q=1}^n \sum_{l=1}^n \left[ \sum_{j=1}^m \frac{\partial \Phi_q}{\partial x_j} \sum_{k=1}^m g_M^{jk} \frac{\partial \Phi_l}{\partial x_k} \right] \frac{\partial f}{\partial y_l} \frac{\partial}{\partial y_q} \\ &= \sum_{q=1}^n \sum_{l=1}^n [D\Phi G_M^{-1} D\Phi^T]_{ql} \frac{\partial f}{\partial y_l} \frac{\partial}{\partial y_q} \\ &= \sum_{q=1}^n \sum_{l=1}^n g_N^{ql} \frac{\partial f}{\partial y_l} \frac{\partial}{\partial y_q} \\ &= \sum_{q=1}^n (\text{grad}_{g_N} f)^q \frac{\partial}{\partial y_q} \\ &= \text{grad}_{g_N} f. \end{aligned}$$

(b) We will make several observations and combine them in the end to obtain the answer. First

$$\Phi^*(\text{div}_{g_N} \Phi_* X) = (\text{div}_{g_N} \Phi_* X) \circ \Phi.$$

Second

$$\text{div}_{g_N} \Phi_* X = \frac{1}{\sqrt{\det G_N}} \sum_{j=1}^n \frac{\partial}{\partial y_j} (\sqrt{\det G_N} (\Phi_* X)^j).$$

Third, the equality

$$G_M(p) = (D\Phi)(p)^T G_N(\Phi(p)) (D\Phi)(p)$$

implies

$$\sqrt{\det G_N(q)} = \frac{\sqrt{\det G_M(\Phi^{-1}(p))}}{|\det D\Phi(\Phi^{-1}(q))|}.$$

Fourth, the equality

$$(\Phi_* X)_1 = D\Phi(\Phi^{-1}(q)) X_{\Phi^{-1}(q)}$$

implies

$$(\Phi_* X)^j(q) = \sum_{l=1}^m \frac{\partial \Phi_j}{\partial x_l}(\Phi^{-1}(q)) X^l(\Phi^{-1}(q)).$$

Fifth

$$\sum_{j=1}^n \frac{\partial \Phi_j}{\partial x_l}(\Phi^{-1}(q)) \frac{\partial}{\partial y_j} (f \circ \Phi^{-1})(q) = \frac{\partial f}{\partial x_l}(\Phi^{-1}(q)).$$

Sixth

$$\frac{d}{ds} \det T(s) = (\det T(s)) \operatorname{Tr} \left( T^{-1}(s) \frac{d}{ds} T(s) \right).$$

Seventh

$$\sum_{j=1}^n \frac{\partial}{\partial y_j} \left( \frac{1}{|D\Phi(\Phi^{-1}(q))|} \frac{\partial \Phi_j}{\partial x_l}(\Phi^{-1}(q)) \right) = 0.$$

To prove this, observe that

$$\frac{\partial \Phi_k}{\partial x_k \partial x_l} = \frac{\partial \Phi_k}{\partial x_l \partial x_k}.$$

Combining all this, we obtain

$$\begin{aligned} & (\operatorname{div}_{g_n} \Phi_* X)(q) \\ &= \frac{|\det D\Phi(\Phi^{-1}(q))|}{\sqrt{\det G_N(\Phi^{-1}(q))}} \\ & \quad \times \sum_{j=1}^n \frac{\partial}{\partial y_j} \left( \frac{\sqrt{\det G_M(\Phi^{-1}(q))}}{|\det D\Phi(\Phi^{-1}(q))|} \sum_{l=1}^m \frac{\partial \Phi_j}{\partial x_l}(\Phi^{-1}(q)) X^l(\Phi^{-1}(q)) \right) \\ &= (\operatorname{div}_{g_M} X)(\Phi^{-1}(q)) + 0. \end{aligned}$$

This implies the desired result.

(c) Using Parts (a) and (b), we obtain

$$\begin{aligned} \Delta_{g_M}(\Phi^* f) &= \operatorname{div}_{g_M}(\operatorname{grad}_{g_M} \Phi^* f) \\ &= \Phi^*(\operatorname{div}_{g_N} \Phi_* \operatorname{grad}_{g_M} \Phi^* f) \\ &= \Phi^*(\operatorname{div}_{g_N} \operatorname{grad}_{g_N} f) \\ &= \Phi^*(\Delta_{g_N} f). \end{aligned}$$

(d) Using that  $\Phi^*g = g$  and the change of variable formula for integrals, we obtain

$$\begin{aligned}\langle \Phi^*f, \Phi^*g \rangle &= \int_M \Phi^*f \Phi^*g dV_g \\ &= \int_M \Phi^*f \Phi^*g dV_{\Phi^*g} \\ &= \int_M \Phi^*(fg dV_g) \\ &= \int_{\Phi(M)} fg dV_g \\ &= \int_M fg dV_g \\ &= \langle f, g \rangle\end{aligned}$$